

Info

This note, that [was found here](#), as a part of [a collection](#) is written (completely with human hands) by [Rupadarshi Ray](#), was created on May 26, 2024 1:23:30 PM, was last modified on September 7, 2026 2:31:09 PM, and was exported on September 7, 2026 2:50:39 PM.

SL(2)(R)

#wiki/Man/R/3

#Wiki/group/Lie

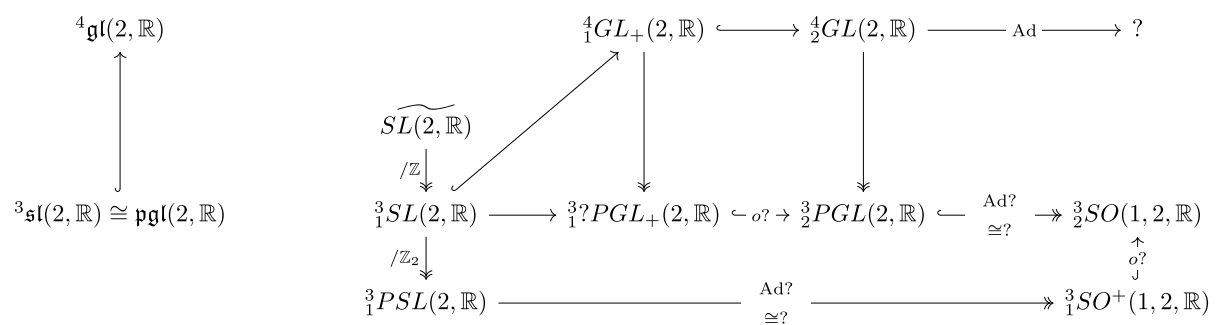
We understand

SL(2)(R) = Sp(2,R)

by definition.

[1]

subgroups and group extensions



subgroups/extensions	quotient
$SL(2)(\mathbb{Z})$	$SL(2)(\mathbb{R})/SL(2)(\mathbb{Z})$
$\{I, -I\}$	$PSL(2)(\mathbb{R})$
$SL(2)(\mathbb{C})$	
discrete subgroups $\iff$ preimage of Fuchsian groups	

types

Given a matrix in $SL(2)(\mathbb{R})$, it has eigenvalues

$\lambda, \lambda^{-1} = \frac{\text{tr}}{2} \pm \frac{\sqrt{\text{tr}^2 - 4}}{2}$

If the discriminant

- If $\text{tr}^2 - 4 < 0$ then

$\lambda, \lambda^{-1} = \frac{\text{tr}}{2} \pm i \frac{\sqrt{-\text{tr}^2 + 4}}{2}$

which has complex norm 1, thus it is a unit complex number, $\lambda \in U(1)$.

- If $\text{tr}^2 - 4 > 0$, then $\lambda \in \mathbb{R}$.
 - Let $\lambda \in \{-1, 1\}$ then

$\text{tr} = \lambda + \frac{1}{\lambda} \in \{-2, 2, 0\}$

which **contradicts** $\text{tr}^2 > 4$.

- Thus $\lambda \in \mathbb{R} \setminus \{-1, 1, 0\}$.

Therefore, we have the following cases:

type	elliptic	parabolic	hyperbolic
$\text{tr}^2 - 4$	< 0	$= 0$	> 0
$ \text{tr} $	< 2	$= 2$	> 2
eigenvalues λ, λ^{-1}	$\lambda \in U(1) \setminus \{-1, 1\}$ $\lambda, \lambda^{-1} = \frac{\text{tr}}{2} \pm i \frac{\sqrt{-\text{tr}^2 + 4}}{2}$	$\lambda = \lambda^{-1} = \frac{\text{tr}}{2} \in \{-1, 1\}$	$\lambda \in \mathbb{R} \setminus \{-1, 1, 0\}$ $\lambda, \lambda^{-1} = \frac{\text{tr}}{2} \pm \frac{\sqrt{\text{tr}^2 - 4}}{2}$
Jordan block in $GL(2)(\mathbb{C})$	$\begin{bmatrix} e^{-ix} & 0 \\ 0 & e^{ix} \end{bmatrix}$	$\pm \begin{bmatrix} 1 & t \\ 0 & 1 \end{bmatrix}$ for $t \in \mathbb{R}$	$\pm \begin{bmatrix} e^{-x} & 0 \\ 0 & e^x \end{bmatrix}$ for $x \in \mathbb{R}, \pm e^x = \lambda$
elements in $SL(2)(\mathbb{R})$ upto conjugacy	conjugate to rotation matrices $R^\theta \in SO(2)(\mathbb{R})$	conjugate to $\pm \begin{bmatrix} 1 & t \\ 0 & 1 \end{bmatrix}$ for $t \in \mathbb{R}$	as it has two distinct real eigenvalues so it is conjugate to $\begin{bmatrix} \lambda & \\ & \lambda^{-1} \end{bmatrix}$
$SL(2)(\mathbb{R}) \curvearrowright \mathbb{R}^2$	elliptic fixed point at 0	parabolic fixed point at 0	hyperbolic fixed point at 0
$SL(2)(\mathbb{R}) \curvearrowright \mathbf{P}(\mathbb{R}^2) = \mathbb{RP}^1$	fixes no line in $\mathbb{R}^2$	fixes exactly one line in $\mathbb{R}^2 \iff$ fixes exactly $\begin{bmatrix} 1 \\ 0 \end{bmatrix}$	fixes exactly two lines in $\mathbb{R}^2$
$SL(2)(\mathbb{R}) \curvearrowright \mathbb{R}H^2$	fixes one point $\iff$ conjugate to stabilizer of i which is $SO(2)(\mathbb{R})$	fixes exactly one point in $\partial \mathbb{R}H^2 \iff$ conjugate to a transformation only fixing $\infty \iff z \mapsto z + t$	fixes exactly two points in $\partial \mathbb{R}H^2 \iff$ conjugate to $z \mapsto \alpha z$

exponential map of SL(2)(R)

det	eigenvalues	type	Jordan block	exponential	trace of exponential
	$\lambda_1, \lambda_2 = \pm \sqrt{-\det}$				
$\det < 0$	$-x, x \in \mathbb{R} \setminus \{0\}$	hyperbolic	$\begin{bmatrix} -x & 0 \\ 0 & x \end{bmatrix}$	$\begin{bmatrix} e^{-x} & 0 \\ 0 & e^x \end{bmatrix}$	$e^{-x} + e^x > 0$
$\det = 0$	0	parabolic	$\begin{bmatrix} 0 & 0 \\ 0 & 0 \end{bmatrix}, \begin{bmatrix} 0 & 1 \\ 0 & 0 \end{bmatrix}$	$\begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix}, \begin{bmatrix} 1 & t \\ 0 & 1 \end{bmatrix}$	2
$\det > 0$	eigenvalues $-ix, ix \in i\mathbb{R}$	elliptic	$\begin{bmatrix} -ix & 0 \\ 0 & ix \end{bmatrix}$	$\begin{bmatrix} e^{-ix} & 0 \\ 0 & e^{ix} \end{bmatrix}$	$2 \cos(x) \geq -2$

Hence,

$$\mathrm{tr}(\exp(\mathfrak{sl}(2,\mathbb{R}))) \geq -2$$

So for example

⋮

Example

The matrix

$$\begin{bmatrix} -2 & \\ & -\frac{1}{2} \end{bmatrix} \in SL(2)(\mathbb{R})$$

is not in the image of the exponential $\mathfrak{sl}(2,\mathbb{R}) \rightarrow SL(2)(\mathbb{R})$.

Let there exists $A \in \mathfrak{gl}(2,\mathbb{R})$ with eigenvalues α, β such that

$$\exp(A) = \begin{bmatrix} -2 & \\ & -\frac{1}{2} \end{bmatrix}$$

Then

$$e^\alpha = -2, e^\beta = -\frac{1}{2}$$

which implies $\alpha, \beta \in \mathbb{C} \setminus \mathbb{R}$ but because A is a real 2x2 matrix it's eigenvalues must be roots of a quadratic polynomial so

$$\alpha = \bar{\beta} \implies |e^\alpha| = |e^\beta|$$

as $|\exp(z)| = e^{\Re(z)}$. But the absolute values do not match $2 \neq \frac{1}{2}$. Thus there is no such $A \in \mathfrak{gl}(2,\mathbb{R})$ either.

generators generating a diffeomorphism

☰

$$\mathbb{R} \times \mathbb{R} \times S^1 \rightarrow SL(2)(\mathbb{R})$$

$$(x, t, \theta) \mapsto \begin{bmatrix} 1 & x \\ 0 & 1 \end{bmatrix} \begin{bmatrix} e^t & 0 \\ 0 & e^{-t} \end{bmatrix} R^\theta$$

>

is a diffeomorphism.

$$(1, 0, 0) \mapsto I_2$$

$$(1, 0, \pi) \mapsto -I_2$$

If we define

$$X := \begin{bmatrix} 1 & 0 \\ 0 & -1 \end{bmatrix}$$

$$Y := \begin{bmatrix} 0 & 1 \\ 0 & 0 \end{bmatrix}$$

$$R := \begin{bmatrix} 0 & -1 \\ 1 & 0 \end{bmatrix}$$

such that

$$\begin{aligned} [X, Y] &= 2Y \\ [X, R] &= -2R - 4Y \\ [Y, R] &= X \end{aligned}$$

so it is not looking that good, but we have

$$\begin{aligned} \exp(tX) &= \begin{bmatrix} e^t & \\ & e^{-t} \end{bmatrix} \\ \exp(tY) &= \begin{bmatrix} 1 & t \\ 0 & 1 \end{bmatrix} \\ \exp(\theta R) &= R^\theta \end{aligned}$$

trace

$$\begin{bmatrix} 1 & x \\ 0 & 1 \end{bmatrix} \begin{bmatrix} e^t & 0 \\ 0 & e^{-t} \end{bmatrix} \begin{bmatrix} \cos \theta & -\sin \theta \\ \sin \theta & \cos \theta \end{bmatrix} = \begin{bmatrix} xe^{-t} \sin(\theta) + e^t \cos(\theta) & xe^{-t} \cos(\theta) - e^t \sin(\theta) \\ e^{-t} \sin(\theta) & e^{-t} \cos(\theta) \end{bmatrix}$$

whose trace is

$$xe^{-t} \sin \theta + \cos \theta (e^t + e^{-t})$$

Current note has 0 direct children and 0 total descendants.

- [squishy](#)
 - $SL(2)(\mathbb{R}) \curvearrowright \mathbb{R}^2$
 - $SL(2)(\mathbb{R}) \curvearrowright H^2_{\mathbb{U}}$
 - SL
 - $SL(2)(\mathbb{R})$
 - $SL(2)(\mathbb{R}) / SL(2)(\mathbb{Z})$

- $SL(2)(\mathbb{Z})$

And it has 15 siblings.

- squishy.
 - SL
 - $\underline{SL}(2)$.
 - $SL(2)(\mathbb{C})$
 - $PSL(n,\mathbb{C})$
 - $SL(2)(\mathbb{R})$
 - $SL(2)(\mathbb{R}) / SL(2)(\mathbb{Z})$
 - H_q
 - $PSL(2)(\mathbb{Z})[2]$
 - $[PSL(2)(\mathbb{Z})[2], PSL(2)(\mathbb{Z})[2\$]]$
 - $PSL(2)(\mathbb{Z})[N]$
 - $SL(3,\mathbb{R})$
 - $SL(2)(\mathbb{Z})$
 - $PSL(2)(\mathbb{Z})$
 - Congruent subgroups of $PSL(2)(\mathbb{Z})$
 - $SL(n,\mathbb{Z})$
 - $SL(2)(\mathbb{Z}_2)$

1. [SL\(2,R\).pdf](#) ↩
2. [webspace.science.uu.nl/~ban00101/lecnotes/sltwoR.pdf](#) ↩