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Manifold with a flow

Definition. Manifold with a smooth flow

A **manifold with a smooth flow** is a pair

$$(M, X)$$

where M is a smooth manifold and $X \in \text{Vec}(M)$.

A *morphism* of two manifolds with flows

$$\phi : (M_1, X_1) \rightarrow (M_2, X_2)$$

is a smooth map $\phi : M_1 \rightarrow M_2$ such that $\phi \circ \exp(tX_1) = \exp(tX_2) \circ \phi$ or equivalently the two vector fields are ϕ -related

$$\text{d}_y \phi(X_y) = X_{\phi(y)}$$

This gives us a category of manifolds with a smooth flow

$$\text{FlowMan}$$

▲ check if two conditions above are equivalent

class	
Trivial	$(M, 0)$
Linear flows	$(\mathbb{R}^n, A)$ where $A \in \text{Mat}(n, \mathbb{R})$
Geodesic flows of (M, g)	$(TM, \exp)$ where (M, g) is a semi-Riemannian manifold and $\exp$ is the geodesic flow
Hamiltonian flows on (M, ω)	$(M, \omega, -\omega^{-1} \text{d}H)$ where (M, ω) is a symplectic manifold and $H \in \mathcal{C}^\infty(M)$
Lagrangian flows	$(TM, \mathcal{E}_L)$ where $\mathcal{E}_L$ is the Euler-Lagrange vector field of $L \in \mathcal{C}^\infty(TM)$
flow of a mechanical manifold $(M, g, \mathcal{F})$	
flow of a <i>conservative</i> mechanical manifold $(M, g, -\text{d}U)$	
Isometric flows	(M, g, X) such that $\mathcal{L}_X g = 0$
Suspension of diffeomorphisms of smooth manifolds	• Functor? $\begin{array}{ccc} \text{End}(\text{Man}) & \rightarrow & \text{FlowMan} \\ M & & \\ \downarrow f & \mapsto & (M_f, \frac{\partial}{\partial t}) \\ M & & \end{array}$

Definition. Immersion and embeddings of manifolds with a smooth flow

An **immersion/embedding** of (M_1, X_1) into (M_2, X_2) is a morphism

$$\phi : (M_1, X_1) \rightarrow (M_2, X_2)$$

where ϕ is an injective immersion/embedding.

	immersions
stationary solution	$(\{\bullet\}, 0) \hookrightarrow (M, X)$
periodic solution	$(\mathbb{R}/\mathbb{Z}, 1) \hookrightarrow (M, X)$
invariant torus	$((\mathbb{R}/\mathbb{Z})^d, \alpha) \hookrightarrow (M, X)$

Definition. Lorentz flows

$$(M, g, F)$$

Let (M, g) be a [semi-Riemannian manifold](#) and

$$F \in \Omega^2(M), \text{d}F = 0$$

then by the symplectic structure on T^*M

$$\omega^{qF} := \text{d}\theta + q\pi_{T^*M}^* F$$

we have the ω^{q^F} -Hamiltonian vector field of the smooth function

$$\begin{aligned} T^*M &\rightarrow \mathbb{R} \\ p &\mapsto \frac{\|p\|_g^2}{2} \end{aligned}$$

Current note has 1 direct children and 2 total descendants.

- [structures based on sets](#)
 - [manifolds](#)
 - [Manifold with a flow](#)
 - [Semi-Riemannian mechanical manifold](#)
 - [Potential mechanical manifold](#) M^N

And it has 20 siblings.

- [structures based on sets](#)
 - [manifolds](#)
 - [Closed aspherical manifolds](#)
 - [ℂ-manifold](#)
 - [Hermitian manifolds](#)
 - [Kahler manifolds](#)
 - [Kahler manifolds of complex dimension 2, AKA Kahler surfaces](#)
 - [smooth ℝ-manifold](#)
 - [Principal bundles over smooth manifolds](#)
 - [Manifold with a flow](#)
 - [ℝ-manifold group \(Lie groups\)](#)
 - [Homogeneous manifold](#)
 - [Finsler manifold](#)
 - [ℝ-manifold semi-Riemannian](#)
 - [Sub-Riemannian manifolds](#)
 - [ℝ-manifold Poisson](#)
 - [ℝ-manifold symplectic](#)
 - [Multisymplectic manifolds](#)
 - [Spin ℝ-manifold](#)
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